

where:

$$\begin{aligned}
 f_1(r) &= \left(\frac{r_2}{r}\right)^2 \log k_2 + k_2^2 \log \left(\frac{r}{r_2}\right) + \log \left(\frac{r_1}{r}\right) \\
 f_2(r) &= -\left(\frac{r_2}{r}\right) \log k_2 + k_2^2 \log \left(\frac{r}{r_2}\right) + \log \left(\frac{r_1}{r}\right) + k_2^2 - 1 \\
 f_3(r) &= -4(1+\nu) \left(\frac{r_2}{r}\right) \log k_2 + 4(1-\nu) \left[ k_2^2 \log \left(\frac{r}{r_2}\right) \right. \\
 &\quad \left. - \log \left(\frac{r}{r_1}\right) \right] - 4(k_2^2 - 1)
 \end{aligned} \tag{20a-c}$$

and where  $(\sigma_r)_c$ ,  $(\sigma_\theta)_c$ , and  $(u)_c$  are given by Equations (13a-c) and (14a, b) for  $k_n = k_2$ ,  $P_{n-1} = P_1$ ,  $P_n = P_2$ , and  $E_n = E_2$ . For a ring segment  $p_1$  and  $p_2$  are related for equilibrium as follows:

$$p_2 = p_1/k_2 \tag{21}$$

Formulas for the constants  $\beta_1$ ,  $G_1$ , and  $M_1$  (functions of  $k_2$ ) are given in Appendix I.  $M_1$  represents a bending moment that causes a bending displacement  $v$  as shown in Equation (19b).

### Pin Segment

The solution for the pin segment is more complicated due to the pin loading at  $r_2$ . The resulting expressions are:

$$\begin{aligned}
 \sigma_r &= (\sigma_r)_c + \frac{4M_2P_1}{\beta_1} f_1(r) + g_{m1}(r) \cos m\theta \\
 \sigma_\theta &= (\sigma_\theta)_c + \frac{4M_2P_1}{\beta_1} f_2(r) + g_{m2}(r) \cos m\theta
 \end{aligned} \tag{22a-c}$$

$$\tau_{r\theta} = g_{m3}(r) \sin m\theta$$

$$\frac{u}{r} = (u)_c + \frac{M_2P_1}{E_2\beta_1} f_3(r) + \frac{G_2P_1}{r} \cos \theta + \frac{1}{E_2} g_{m4}(r) \cos m\theta \tag{23a, b}$$

$$\frac{v}{r} = \frac{8M_2P_1}{E_2\beta_1} (k_2^2 - 1) \theta - \frac{G_2P_1}{r} \sin \theta + \frac{1}{E_2} g_{m5}(r) \sin m\theta$$

where  $(\sigma_r)_c$ ,  $(\sigma_\theta)_c$ , and  $(u)_c$  are again given by Equations (13a-c) and (14a, b) for  $k_n = k_2$ ,  $p_{n-1} = p_1$ ,  $p_n = p_2$ , and  $E_n = E_2$ . For a pin segment  $p_2$  is related to  $p_1$  as follows:

$$p_2 = \frac{(m^2-1)(1+2\cos\pi/m)}{2(m^2-2)(1+\cos\pi/m)} \left(\frac{p_1}{k_2}\right) \quad (24)$$

where  $m$  defined as

$$m = 2N_s \quad (25)$$

and where  $N_s$  is the number of segments per disc.

The functions  $f_1(r)$ ,  $f_2(r)$ , and  $f_3(r)$  are again given by Equations (20a-c) and  $\beta_1$ ,  $G_2$ ,  $M_2$ ,  $g_{m1}$ , ...,  $g_{m5}(r)$  are given in Appendix I.

The elasticity solutions now can be used to determine formulas for maximum pressure capability from the fatigue relations. This is done in the next section.